

Faster Fully Dynamic Matching With Small Approximation Ratios

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Static Maximum Matching

- **Unweighted n-vertex, m-edge** graph **G**
- **Goal**: find a maximum cardinality matching (**MCM**) in **G**
- **Exact algorithms**:
 - $O(mn^{1/2})$ [Micali, Vazirani FOCS 1980]
 - $O(\text{MM}(n)) \sim O(n^{2.36})$ [Sankowski FOCS 2004]
- **Exact algorithms for bipartite graphs**:
 - $O(mn^{1/2})$ [Hopcroft-Karp, SICOMP, 1973]
 - $\tilde{O}(m^{10/7})$ [Madry FOCS 2013].
- **Approximate algorithms**:
 - $(1 + \epsilon)$ -approximation in time $\tilde{O}(m/\epsilon)$

Dynamic Exact MCM

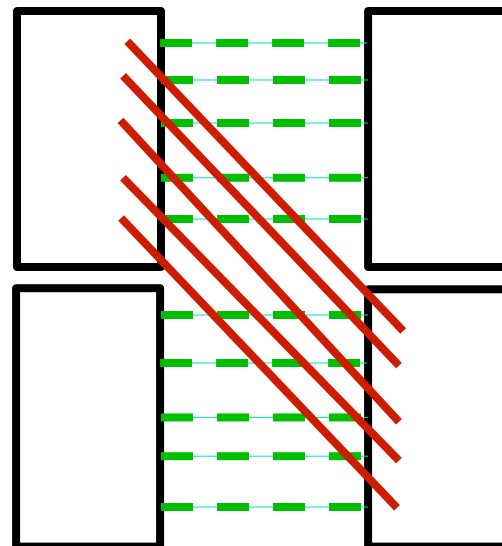
- **Dynamic** – edges are inserted and deleted, we maintain a matching
- **Trivial:**
 - Recompute - $O(mn^{1/2})$ or $O(MM(n))$ per update
 - Find augmenting path - $O(m)$ per update
- **Sankowski's algorithm:**
 - $O(n^{1.495})$ randomized [SODA 2007].
- What about dynamic **approximate** MCM?
- Note: The “adwords” problem is a different dynamic matching problem

Dynamic Approximate MCM

- Variants:
 - Randomized vs. **deterministic**
 - **Worst-case** vs. **amortized**
 - **Bipartite** vs. **non-bipartite**
- Two very different problems:
 - 2-or-worse approximation.
 - Better-than-2 approximation.

Maximal Matching

- ❑ Maximal: can't add an edge to the matching
- ❑ Maximal \neq Maximum
- ❑ Maximal matching is 2-approximate.
- ❑ Maximal matching purely local
 - If x and y are free, can always match x and y , without considering rest of graph.
- ❑ 1.99 approximation not purely local.



- ❑ **Maximum** has size 10
- ❑ **Maximal** has size 5

Dynamic Approximate MCM (before us)

- **2-or-worse Approximation:**
 - $O(\log(n))$ update, 2-approximation, randomized [Baswana, Gupta, Sen, FOCS 2011]
- **Better-than-2 approximation:**
 - $O(m^{1/2})$ update, $(1+\epsilon)$ -approximation. [Gupta, Peng, FOCS 2013]
- **Deterministic Algorithms:**
 - $O(m^{1/2})$ update, $(1+\epsilon)$ -approximation [Gupta, Peng]
 - $O(m^{1/3})$ update, $(3+\epsilon)$ -approximation [Bhattacharya, Henzinger, Italiano, SODA 2015]
- **Our Goals:**
 - faster better-than-2 approximation
 - faster deterministic algorithm.

Our results

□ Recall State of the art:

- 2-approx., $O(\log n)$ update, randomized
- $(1+\varepsilon)$ -approx., $O(m^{1/2})$ update, deterministic
- $(3+\varepsilon)$ -approx., $O(m^{1/3})$ update, deterministic

□ Our results:

- $(3/2+\varepsilon)$ -approx., $O(m^{1/4})$ update, deterministic
- Same bounds (different algorithm and analysis for bipartite (ICALP 2015) and general (SODA 2016) graphs
- Fastest better-than-2 approximation.
- Fastest deterministic algorithm for **any** constant approx.
- Also: better results for small arboricity graphs (see papers)

Subsequent to our results

□ Recall our results:

- $(3/2+\epsilon)$ -approx., $O(m^{1/4})$ update, deterministic
- Same bounds (different algorithm and analysis for bipartite (ICALP 2015) and general (SODA 2016) graphs
- Fastest better-than-2 approximation.
- Fastest deterministic algorithm for **any** constant approx.
- Also: better results for small arboricity graphs

□ Simultaneous:

- Even better results for small arboricity: [Peleg, Solomon **SODA 2016**]

□ Subsequent: [Bhattacharya, Henzinger, Nanongkai, STOC 2016]

- $O(\text{polylog } n)$ update, $(2+\epsilon)$ -approximation
- $O(n^\epsilon)$ update, <2 -approximation of value in bipartite graphs

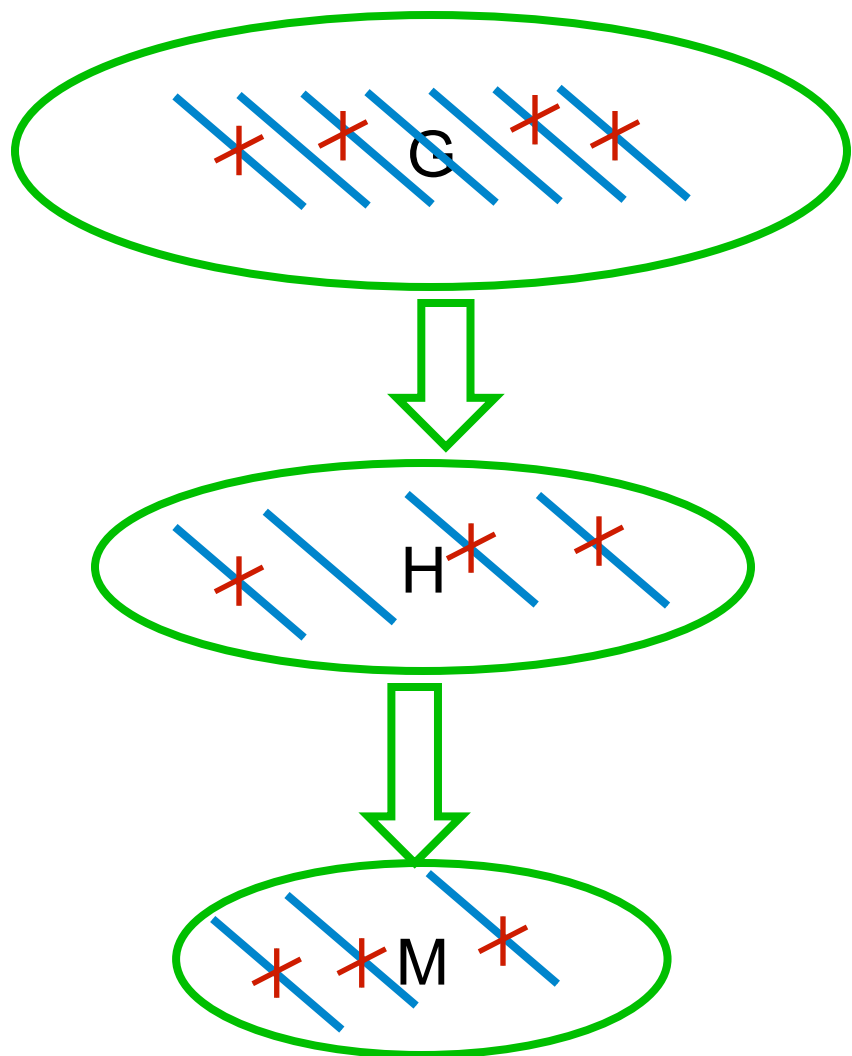
Characterizing Approximate Matchings

- **Exact matching:** matching M contains no augmenting paths $\rightarrow M$ is maximum
- **2-approximate matching:** matching M is maximal $\rightarrow M$ is 2-approximate
 - **Maximal:** for every edge (u,v) , u or v (or both) is matched
- **Better-than-2 approximation:** if all augmenting paths w.r.t M have length $> (2k-1)$ then M is a $(1+1/k)$ -approx. matching.
 - All path lengths $> 1 \rightarrow 2$ -approximation
 - All path lengths $> 3 \rightarrow 3/2$ -approximation.
 - All path lengths $> 1/\varepsilon \rightarrow (1+O(\varepsilon))$ -approximation.
 - Unlike maximality, cannot be expressed in terms of local constraints on each edge

Characterizing Approximate Matchings

- **Ideally show:** A matching M that satisfies some set of local constraints is a $(1+\epsilon)$ -approximate matching (or at least better-than-2 approximate).
 - We were unable to do this even for bipartite graphs.
- **Our results:** use local constraints to characterize a **small subgraph** H of G such that H is guaranteed to contain a large matching. (used in previous work, but with different small subgraph, typically fractional or b -matching.)
- **Recall** a b -matching is a subgraph where each vertex has degree at most b

Matching-Preserving Subgraph



□ What we want from H :

- 1. M is easy to maintain in H
- 2. Large matching in H is relatively large w.r.t to G
- 3. Easy to maintain H dynamically.

Edge Degree Constrained Subgraph (EDCS)

- **Defn:** $\mu(H)$ = size of maximal matching in H .
- **Defn:** $\delta_H(u)$ = degree of u in H .

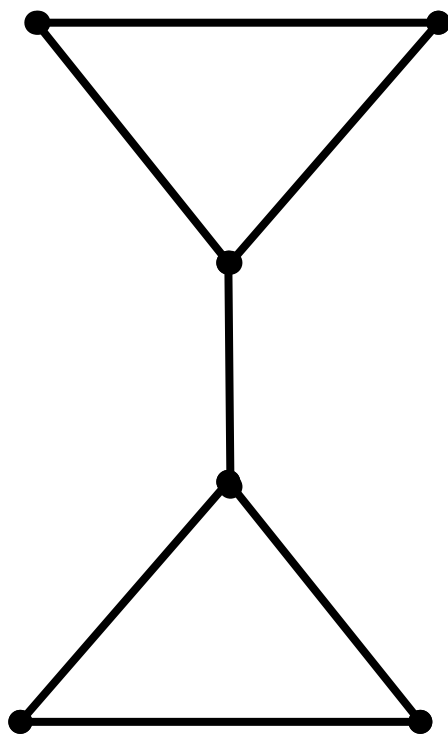
- A subgraph H of G is an **EDCS(B)** if it has the following properties (B is parameter of our choosing):
 - **1.** For each edge (u,v) in H ,
$$\delta_H(u) + \delta_H(v) \leq B$$
 - **2.** For each edge (u,v) in $G \setminus H$,
$$\delta_H(u) + \delta_H(v) \geq B(1 - \epsilon^2)$$

Example of EDCS

□ Example of EDCS(3):

- **1.** For each edge (u,v) in H , $\delta_H(u) + \delta_H(v) \leq 3$
- **2.** For each edge (u,v) in $G \setminus H$, $\delta_H(u) + \delta_H(v) \geq 2$

$$\mu(G) = 3$$



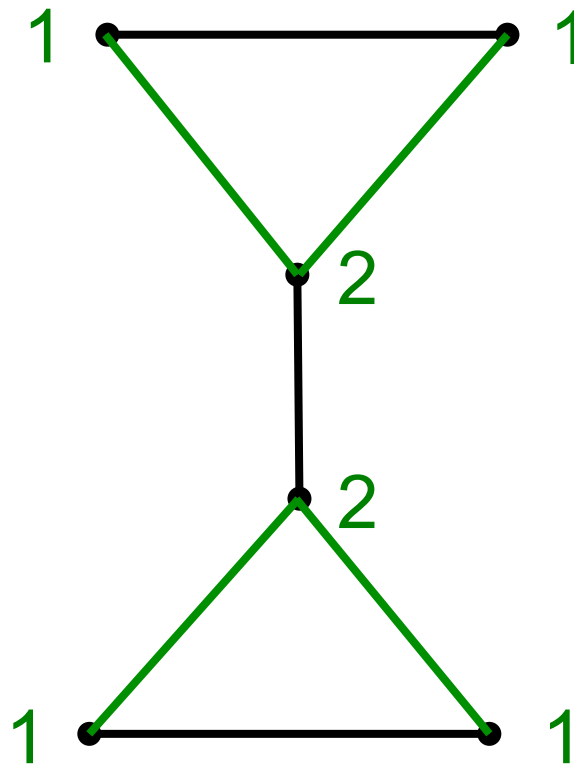
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$$\mu(G) = 3$$

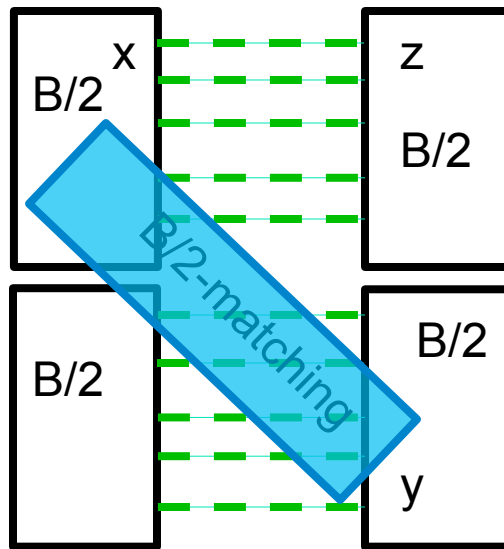
$$\mu(H) = 2$$



Example of a non-EDCS

□ Example of EDCS(B):

- 1. For each edge (u,v) in H , $\delta_H(u) + \delta_H(v) \leq B$
- 2. For each edge (u,v) in $G \setminus H$, $\delta_H(u) + \delta_H(v) \geq B(1 - \epsilon^2)$



$$\delta_H(x) + \delta_H(z) = B/2 + 1$$

$$\delta_H(x) + \delta_H(y) = B$$

- B/2-matching (complete bipartite graph) only contains a 2-approximation to the maximum matching
- B/2-matching is not an EDCS
- Our “local” algorithm will recognize this

What do we need to do?

- 1. Prove the main theorem:** Let H be an $\text{EDCS}(B)$ of a graph G . Then: $\mu(H) \geq (2/3 - \epsilon) \mu(G)$
 - only true if $B > 4/\epsilon^2$
 - H has bounded degree B
- 2. Algorithm problem 1:** Show how to maintain an $\text{EDCS}(B)$ quickly in a dynamic graph
- 3. Algorithm problem 2:** Maintain a $(1 + \epsilon)$ approx. matching M in H
 - Easy because H has bounded degree [Gupta, Peng, FOCS 2013]

3/2-approximation follows

- $\text{Size}(M) \geq (1-\varepsilon)\mu(H) \geq (2/3-\varepsilon)(1-\varepsilon)\mu(G) = (2/3 - O(\varepsilon)) \mu(G)$

- Now, let's briefly talk about maintaining an EDCS, and then the main theorem

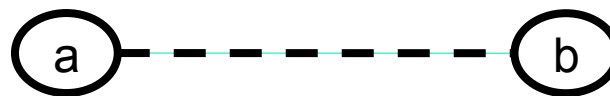
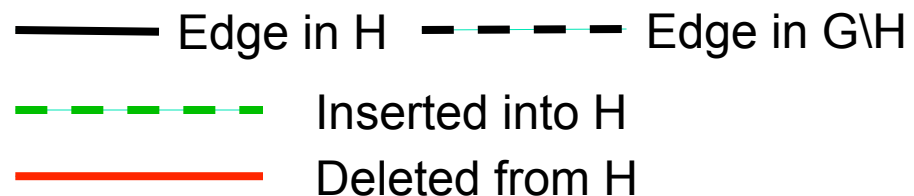
Maintaining an EDCS (bipartite graph)

□ EDCS(B):

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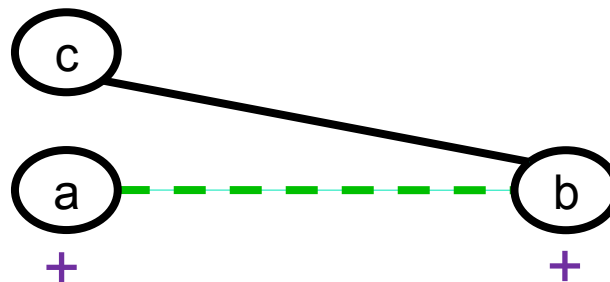
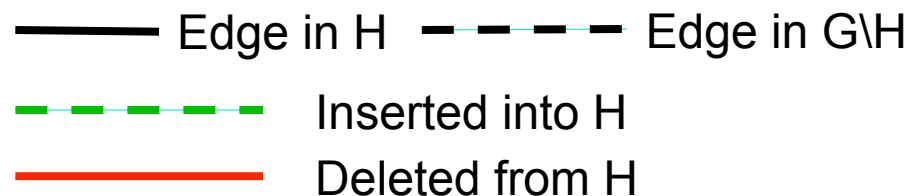
$$\delta_H(u) + \delta_H(v) \geq B(1 - \epsilon^2)$$



Maintaining an EDCS (bipartite graph)

□ EDCS(B:

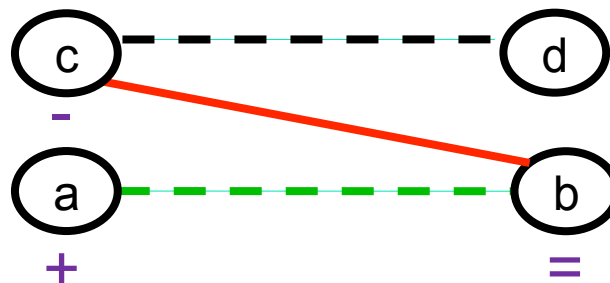
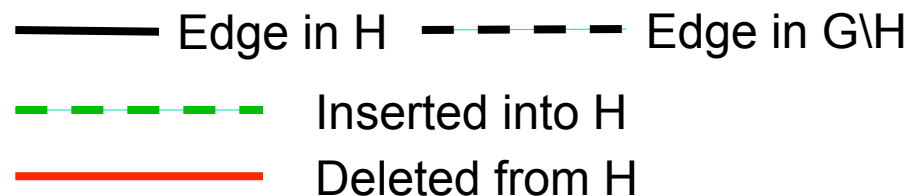
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Maintaining an EDCS (bipartite graph)

□ EDCS(B):

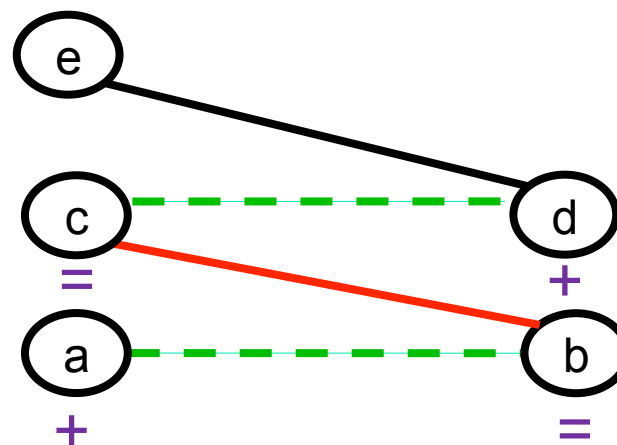
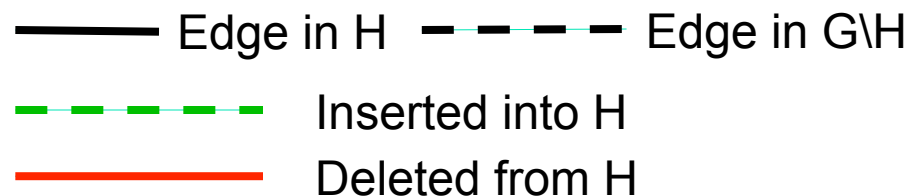
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Maintaining an EDCS (bipartite graph)

□ EDCS(B):

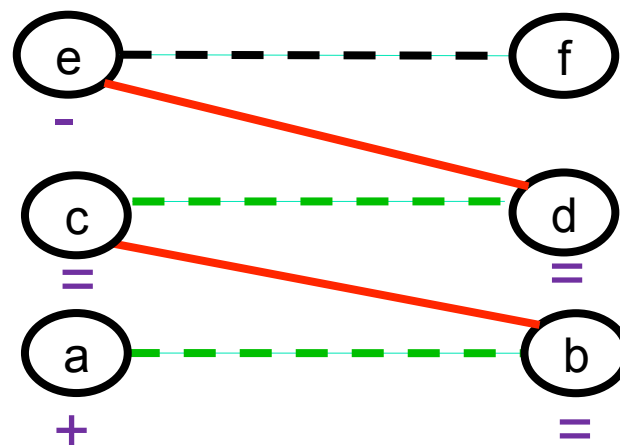
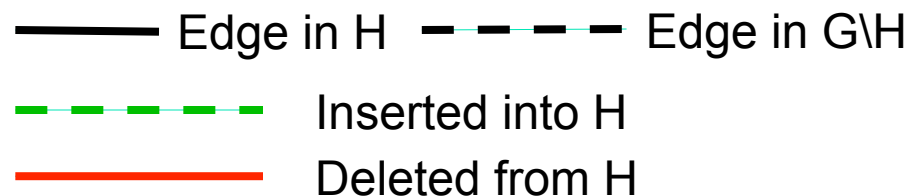
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Maintaining an EDCS (bipartite graph)

□ EDCS(B):

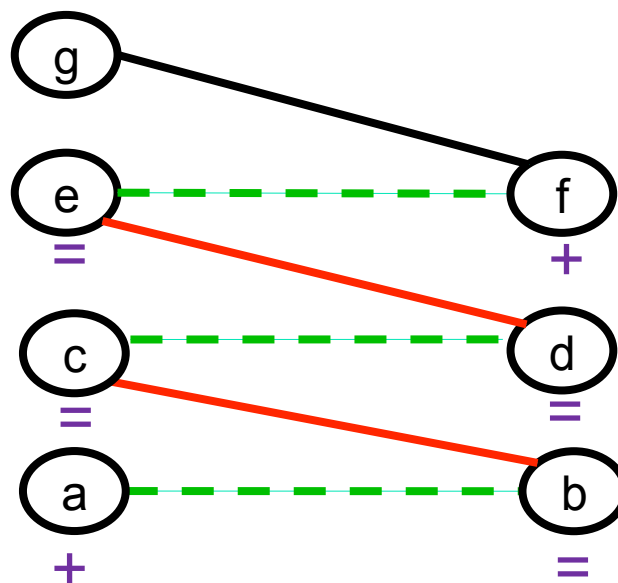
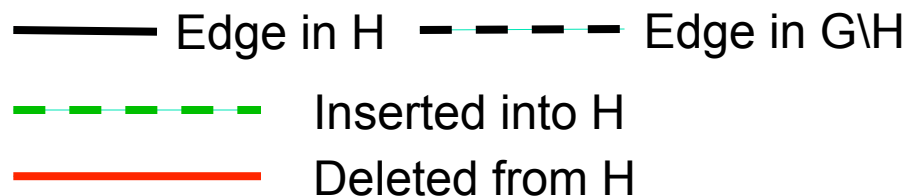
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Maintaining an EDCS (bipartite graph)

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Maintaining an EDCS (bipartite graph)

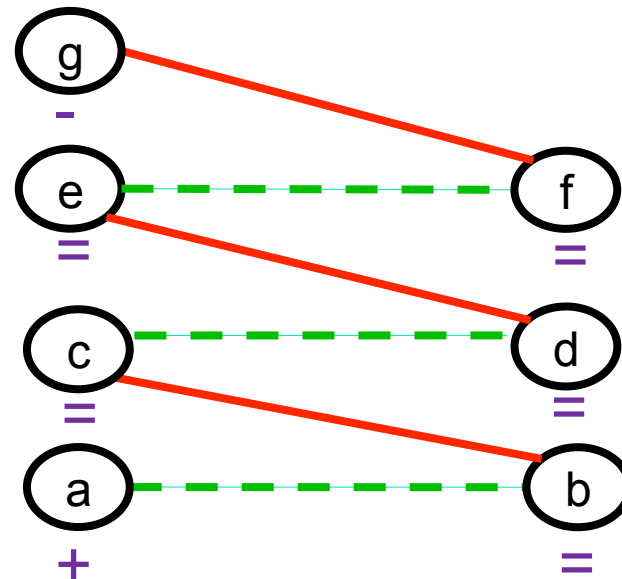
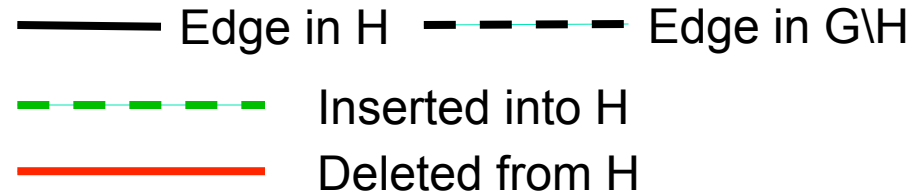
EDCS(B, λ):

- 1. For each edge (u,v) in H ,
 $\delta_H(u) + \delta_H(v) \leq B$
- 2. For each edge (u,v) in G/H ,
 $\delta_H(u) + \delta_H(v) \geq B(1 - \epsilon^2)$

Can show: only need $O(\epsilon^{-2})$ rebalances

Difference from augmenting path:
Any sequences of rebalances will work and be short.

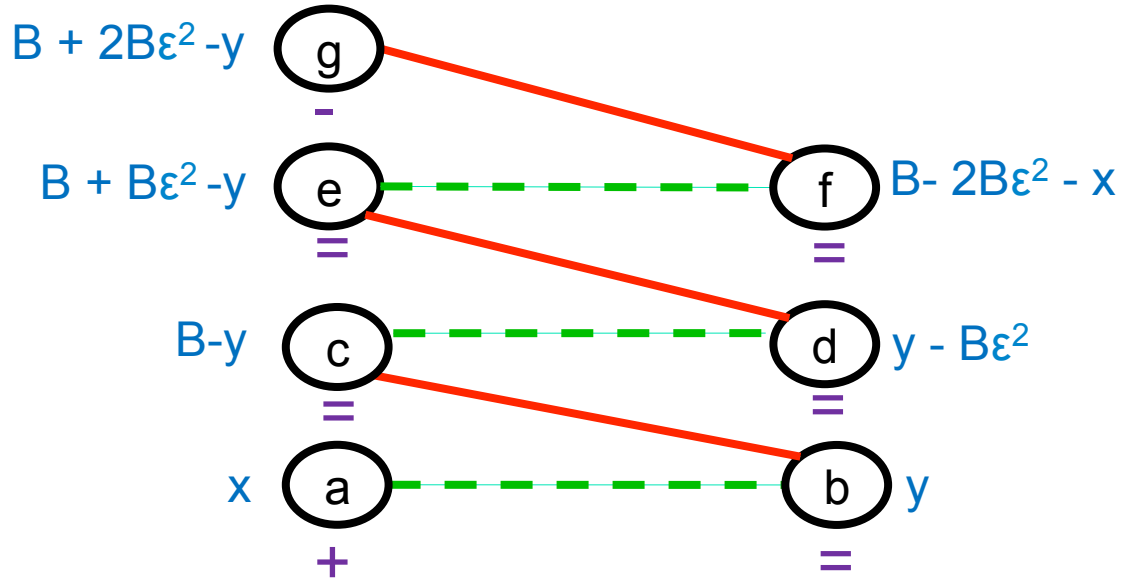
- No “backtracking”



Bipartite running time

EDCS(B):

- 1. For each edge (u,v) in H , $\delta_H(u) + \delta_H(v) \leq B$
- 2. For each edge (u,v) in $G \setminus H$, $\delta_H(u) + \delta_H(v) \geq B(1 - \epsilon^2)$

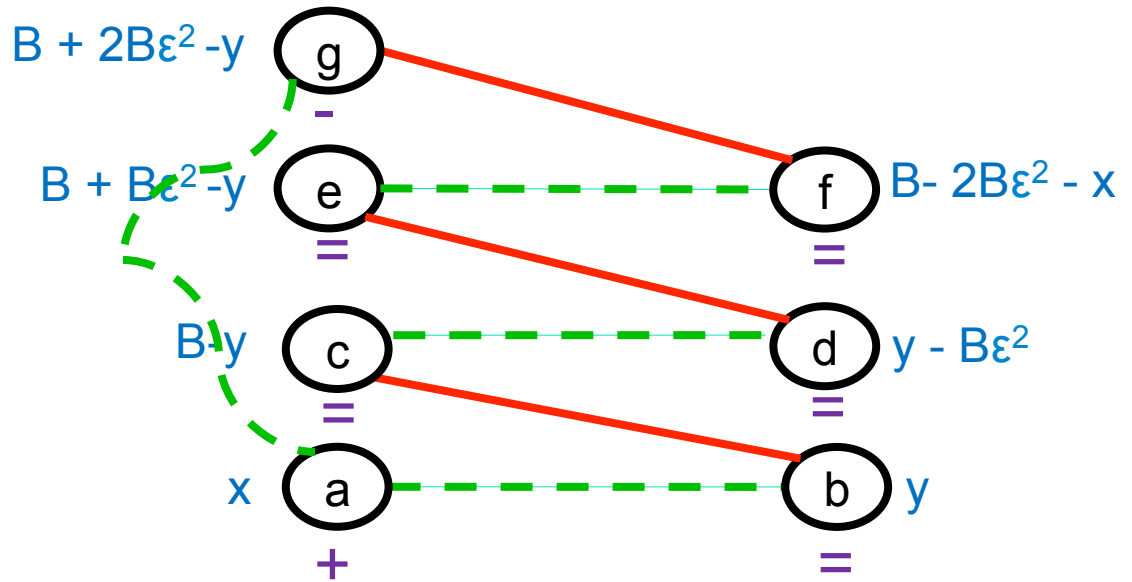


- Only $O(\epsilon^{-2})$ rebalances per edge change in G
- Easy: Rebalance a node in time $O(\text{degree}) = O(n)$
- Can do: Rebalance in time $O(\text{arboricity})$ (dynamic orientation++)
- General Graphs: arboricity = $m^{1/2}$
- Lazy Rebalancing: buffer of $B\epsilon^{-2}$ between EDCS properties
- Resulting worst case update time: $O(m^{1/2} \epsilon^{-2} / B)$

NonBipartite running time

EDCS(B, λ):

- 1. For each edge (u,v) in H , $\delta_H(u) + \delta_H(v) \leq B$
- 2. For each edge (u,v) in $G \setminus H$, $\delta_H(u) + \delta_H(v) \geq B(1 - \epsilon^2)$

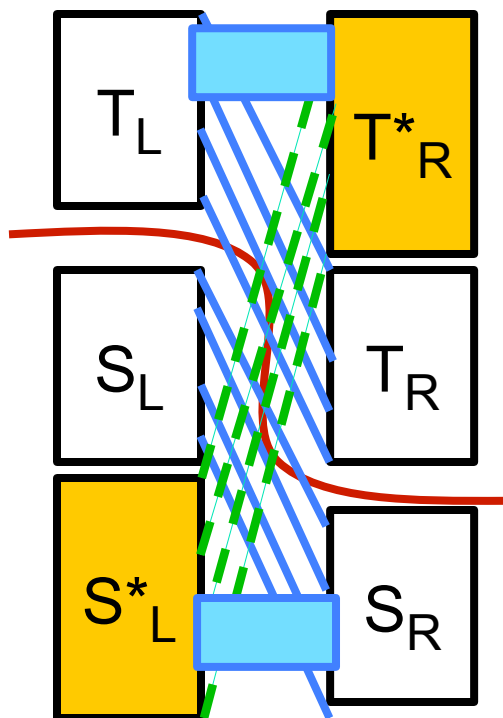


- Can't show $O(\epsilon^{-2})$ rebalances per edge change in G , but can show a similar amortized bound, using
 - Potential function
 - Dynamic orientation
 - Lots of data structures
- Implicitly dealing with blossoms

Showing an EDCS contains a large matching

Proof sketch for bipartite graphs

- The residual graph defined by the maximum matching in H (n vertices per side).
- **Contradiction Assumption:** $\mu(H) < (2/3 - \epsilon)n$



- H contains no edges crossing cut.
- $|S^*_L| = |T^*_R| \geq (n/3)(1 + \epsilon)$
- **Assume:** $|S_L| = |S_R| = |T_L| = |T_R| < n/3$
- $\geq (n/3)(1 + \epsilon)$ disjoint crossing edges in $G \setminus H$
- **Assume:** crossing edges go from S^*_L to T^*_R
- **Then:** average degree in H of $|S^*_L| \cup |T^*_R| \geq B/2(1 - \epsilon^2) \sim B/2$ (Prop. 2)
- Can't fit degree of S^*_L in smaller S_R (Prop. 1)

□ **1.** For edge (u, v) in H , $\delta(u) + \delta(v) \leq B$

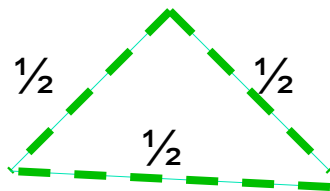
□ **2.** For edge (u, v) in $G \setminus H$, $\delta(u) + \delta(v) \geq B(1 - \epsilon^2)$

Main Theorem in Nonbipartite Graphs

- **Defn:** a subgraph **H** of **G** is an **EDCS(B)** if:
 - 1. For each edge (u,v) in **H**, $\delta_H(u) + \delta_H(v) \leq B$
 - 2. For each edge (u,v) in $G \setminus H$, $\delta_H(u) + \delta_H(v) \geq B(1 - \epsilon^2)$
- **Main Thm:** if **H** is an EDCS(B), $\mu(H) \geq (2/3 - \epsilon)\mu(G)$
- **Idea:** explicitly construct a large **fractional matching** in **H**
 - Let $\text{val}(u,v)$ be the fractional value on edge (u,v) in a fractional matching
 - $\text{val}(u,v)$ will depend on $\delta_H(u)$ and $\delta_H(v)$
- Simplifies several proofs for bipartite case
- **Problem:** integrality gap in nonbipartite graphs

Fractional Matching

- **Dfn:** let $\mu_f(G)$ be the size of maximum fractional matching in G
- **Bipartite Graphs:** $\mu_f(G) = \mu(G)$
- **Nonbipartite Graphs:** $\mu(G) \geq (2/3)\mu_f(G)$
- **Can show:** if H is an EDCS(B), then
$$\mu_f(H) \geq (2/3 - \varepsilon)\mu(G)$$
- **Not good enough:**
$$\mu(H) \geq (2/3)\mu_f(H) \geq (4/9 - \varepsilon)\mu(G)$$



α -Restricted Fractional Matching

- **Dfn:** Let $\text{val}(u,v)$ be the fractional value on edge (u,v) in a fractional matching
- A fractional matching is **α -restricted** ($\alpha < 1$) if for every edge (u,v) either $\text{val}(u,v) = 1$ or $\text{val}(u,v) \leq \alpha$
- **Dfn:** let $\mu_f^\alpha(G)$ be the maximum value of an α -restricted fractional matching in G

- **Classic Thm:**

$$\mu(G) \geq (2/3)\mu_f(G)$$

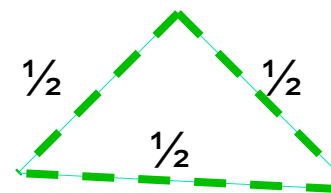
- **Our Thm:**

$$\mu(G) \geq (\alpha/(\alpha+1)) \mu_f^\alpha(G)$$

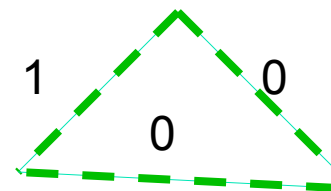
- **Corollary:**

$$\mu(G) \geq (1-\varepsilon) \mu_f^\varepsilon(G)$$

$\alpha=1/2$



$\alpha=1/3$



EDCS contains a large ε -restricted matching

- **Main Thm:** If a subgraph H is an EDCS(B):

$$\mu(H) \geq (2/3 - \varepsilon) \mu(G)$$

- **Main Lemma:** If a subgraph H is an EDCS(B):

$$\mu_f^\varepsilon(H) \geq (2/3 - \varepsilon) \mu(G)$$

- **Main Lemma \rightarrow Main Theorem:**

$$\mu(H) \geq (1 - \varepsilon) \mu_f^\varepsilon(H) \geq (2/3 - \varepsilon)(1 - \varepsilon)\mu(G) = (2/3 - O(\varepsilon))\mu(G)$$

Explicit Construction

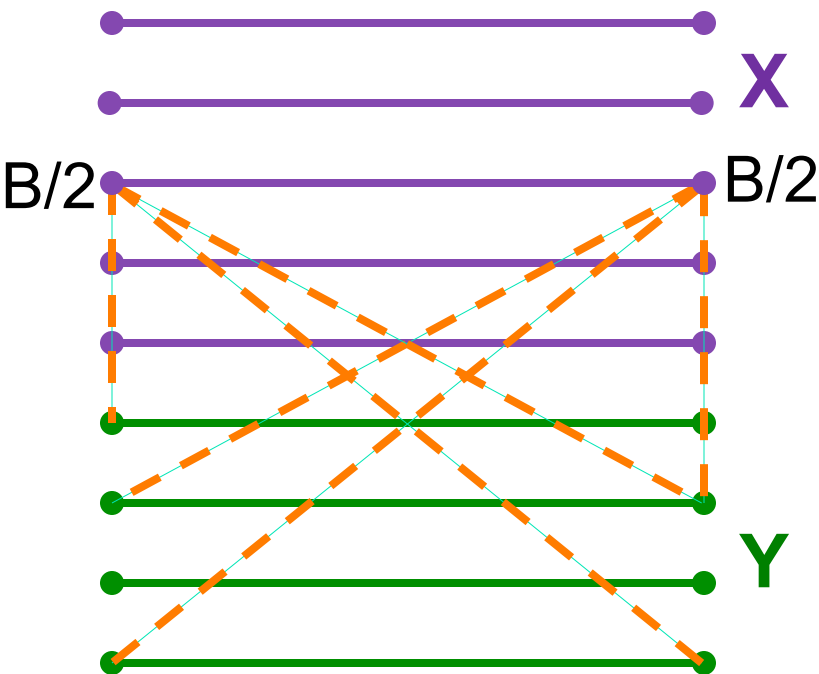
- Given some subgraph H that is an EDCS(B)
 - **1.** For each edge (u,v) in H , $\delta_H(u) + \delta_H(v) \leq B$
 - **2.** For each edge (u,v) in $G \setminus H$, $\delta_H(u) + \delta_H(v) \geq B(1 - \varepsilon^2)$
- **Want to show:** can construct an ε -restricted fractional matching M_H of H such that:
$$\text{val}(M_H) \geq (2/3 - \varepsilon)\mu(G)$$
- Very involved proof. For this presentation will make many simplifying assumptions.

Proof Sketch of main theorem

- **Simplified** EDCS constraints
(u,v) in H: $\delta_H(u) + \delta_H(v) \leq B$
(u,v) in $G \setminus H$: $\delta_H(u) + \delta_H(v) \geq B$

Maximum matching M_G

Note: $|X| + |Y| = 2\mu(G)$

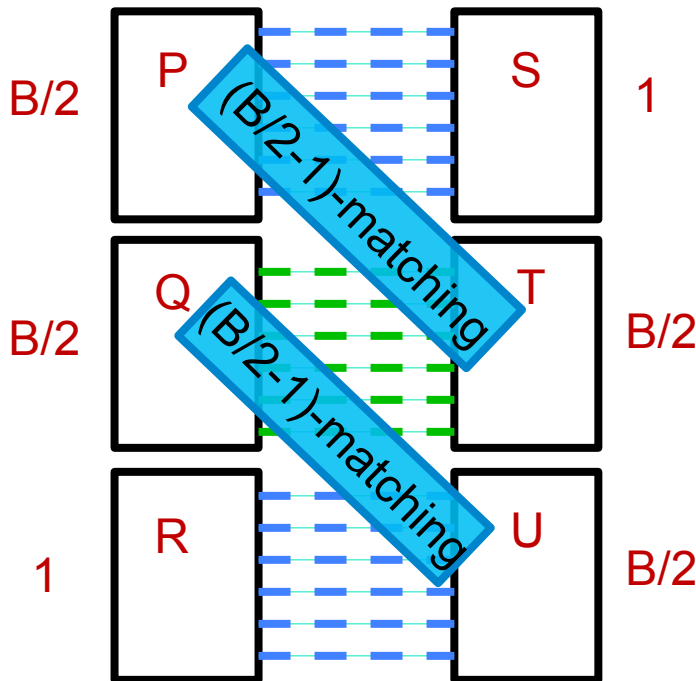


- **Big Assumption:** if edge (u,v) in $X-X$: $\delta_H(u) = \delta_H(v) = B/2$
- **Medium Assumption:** All edges in H incident to Y
- **Fractional Matching:** for each edge (u,v) in $X-Y$, $\text{val}(u,v) = 2/B$
 - Legality: all relevant vertices have degree at most B/2
- **Total value:** $|X|(B/2)(2/B) = |X|$
- **Case 1:** $|X| \geq 2\mu(G)/3$
- **Case 2:** $|Y| \geq 4\mu(G)/3$. At least $2\mu(G)/3$ edges in $Y-Y$
- **Actual proof:** mix two cases. Probabilistic method.

EDCS is only a 3/2-approximation.

□ Unweighted EDCS(B):

- 1. For each edge (u,v) in H , $\delta_H(u) + \delta_H(v) \leq B$
- 2. For each edge (u,v) in $G \setminus H$, $\delta_H(u) + \delta_H(v) \geq B(1 - \epsilon^2)$

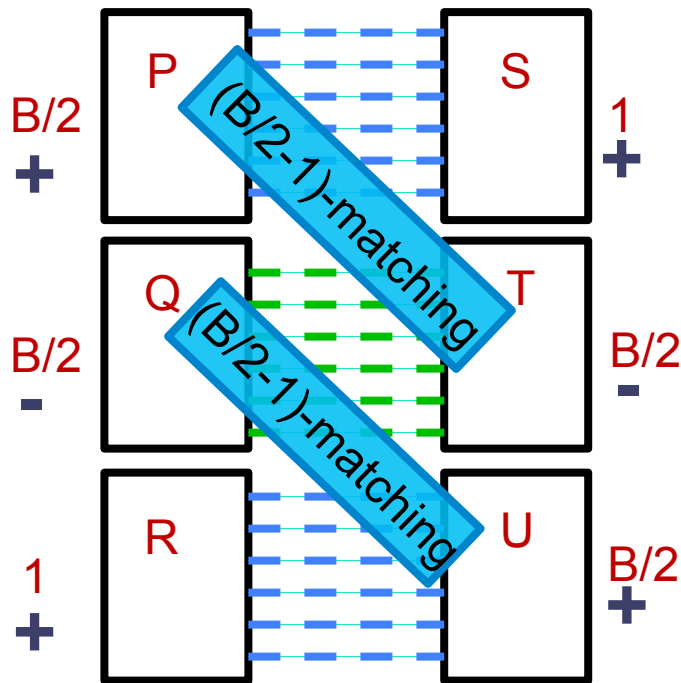


- Blue edges = In H
- Green edges = In $G \setminus H$
- $\mu(H) = 2n/3 = 2/3 \mu(G)$
- **Note:** edges between P-S and R-U have edge degree $\ll B(1 - \epsilon^2)$
- H is a valid EDCS only because constraint 2 only applies to edges in $G \setminus H$

Weighted EDCS

- Unweighted EDCS(B):
 - 1. For each edge (u,v) in H , $\delta_H(u) + \delta_H(v) \leq B$
 - 2. For each edge (u,v) in $G \setminus H$, $\delta_H(u) + \delta_H(v) \geq B(1 - \epsilon^2)$
- **Definition:** $G^B = G$, but with B copies of each edge
- Weighted EDCS(B):
 - Equivalent to Unweighted EDCS(B) on G^B
 - Degree $\delta_H(u)$ now takes into account multiplicity.
 - Multiplicities can be ignored when computing the matching M in H because in M max degree = 2.
- **Constraint 2 in a weighted EDCS:**
 - Some copy of edge (u,v) is always in $G \setminus H$
 - So: for each edge (u,v) in G , $\delta_H(u) + \delta_H(v) \geq B(1 - \epsilon^2)$

Unweighted VS. Weighted



- Blue edges = In H
- Green edges = In $G \setminus H$
- Unweighted EDCS:
 - 1. For edge (u,v) in H , $\delta(u) + \delta(v) \leq B$
 - 2. For edge (u,v) in $G \setminus H$, $\delta(u) + \delta(v) \geq B(1 - \epsilon^2)$
- Weighted EDCS:
 - Each edge has multiplicity B
 - 1. For edge (u,v) in H , $\delta(u) + \delta(v) \leq B$ (same)
 - 2. For edge (u,v) in G , $\delta(u) + \delta(v) \geq B(1 - \epsilon^2)$

□ Unweighted EDCS: $\mu(H) = 2n/3$.

□ Weighted EDCS: P - S and R - U edges violate **Prop. 2**.

○ Must add weight to P - S and R - U edges.

○ Must then remove weight from P - T and Q - U edges (**Prop. 1**)

○ Must now add weight to Q - T edges (**Prop. 2**).

Weighted EDCS

- Can show that in a weighted EDCS satisfies $\mu(H) \geq (1 - \epsilon) \mu(G)$
- Can only maintain a weighted EDCS efficiently in low arboricity bipartite graphs
- Intuitively, with a weighted EDCS, deleting 1 edge in G can delete a large amount of weight in H .

Review

- Main Result: $O(m^{1/4})$ update time, $(3/2-\varepsilon)$ -approx.
 - Fastest better than 2-approximation
 - Fastest deterministic algorithm for any constant approx.
- EDCS(B): subgraph H such that
 - 1. For each edge (u,v) in H , $\delta_H(u) + \delta_H(v) \leq B$
 - 2. For each edge (u,v) in $G \setminus H$, $\delta_H(u) + \delta_H(v) \geq B(1 - \varepsilon^2)$
- **Main Theorem:** $\mu(H) \geq (3/2-\varepsilon) \mu(G)$
 - Techniques very different for bipartite and nonbipartite case
- Lots of dynamic graph and graph orientation details to achieve running time

Open Problems

- ❑ Can we maintain a $(1 + \epsilon)$ approximation in update time $O(m^{1/2-c})$ update time for any fixed $c > 0$?
- ❑ How well can we approximate matching in polylog update time
- ❑ Very interesting even on bipartite graphs, with randomization and amortization.
- ❑ Weighted EDCS may be helpful